

Vorticity and curvature at a general material surface

Blas Herrera^{a)}

Departament d'Enginyeria Informàtica i Matemàtiques, Universitat Rovira i Virgili,
Avinguda Països Catalans 26, Tarragona 43007, Spain

(Received 1 December 2009; accepted 1 April 2010; published online 28 April 2010)

If S is a general material surface in a flow in the space, we show the relationship between the three components of the vorticity field on S and the curvatures of the streamlines of the tangential component of the velocity field (geodesic torsion, normal curvature, and geodesic curvature); and we show the relationship for the case of a general free surface. We present geometric formulae relating vorticity flux, from S , and curvatures of S (Gaussian curvature, mean curvature, curvatures of the streamlines of the tangential component of the velocity field); and we show the formulae for the case of a general free surface. © 2010 American Institute of Physics. [doi:10.1063/1.3407653]

I. INTRODUCTION

The first part of this introduction, before Eq. (1.7), is dedicated to fix the notation. We consider a general material surface S in a flow \mathcal{F} in \mathbb{R}^3 ; that is, let S be a C^∞ -smooth surface of \mathbb{R}^3 (oriented Euclidean three-dimensional space) tangent or not to the C^∞ -smooth velocity vector field $\vec{u}=\vec{u}(p,t)$ of the flow at any fixed time $t=t_0$.

Then we can consider the trio $(\vec{u}, \vec{\omega}, D)$ formed by the smooth velocity vector field of \mathcal{F} at a given time t_0 , its vorticity field: curl (\vec{u}) , and its 2-covariant rate-of-strain tensor field, respectively. We denote the vectors and the tensor, at the point p , by $\vec{u}(p)$, $\vec{\omega}(p)$, and D_p , respectively. Let \vec{x} be a parametrization of the smooth surface S :

$$\begin{aligned} \vec{x}: U \subset \mathbb{R}^2 \rightarrow \mathbb{R}^3, (\theta_1, \theta_2) &\mapsto \vec{x}(\theta_1, \theta_2) \\ &= [x(\theta_1, \theta_2), y(\theta_1, \theta_2), z(\theta_1, \theta_2)]. \end{aligned} \quad (1.1)$$

Let $\vec{N}(\theta_1, \theta_2)$ be the normal vector given by the parametrization $\vec{N} = \frac{\partial \vec{x}}{\partial \theta_1} \times \frac{\partial \vec{x}}{\partial \theta_2} / \left\| \frac{\partial \vec{x}}{\partial \theta_1} \times \frac{\partial \vec{x}}{\partial \theta_2} \right\|$.

For $p \in S$ we know that exist an enough small three-dimensional neighborhood Ω in the space such that $\forall q \in \Omega$,

$$\begin{aligned} \vec{u}(q) &= \vec{u}_t(q) + u_3 \vec{N}(q), \\ \vec{u}_t(q) &= u_1(q) \frac{\partial \vec{x}}{\partial \theta_1}(q_s) + u_2(q) \frac{\partial \vec{x}}{\partial \theta_2}(q_s), \end{aligned} \quad (1.2)$$

$$u_3 \vec{N}(q) = u_3(q) \vec{N}(q_s),$$

where $q_s \in S \cap \Omega$, $q = p + \lambda \vec{N}(q_s)$, $\lambda \in (-\varepsilon, \varepsilon)$, $\vec{u}_t(q)$ is the tangent component vector field of the velocity in Ω to the surface S , that is $\vec{u}_t(q) \cdot \vec{N}(q_s) = 0$ (where \cdot denotes the scalar product), and $u_3(q)$ is the scalar vertical component of the velocity in Ω to S .

Let $\vec{v} = \vec{u}_t(q_s)$ be the tangent velocity vector field on $S \cap \Omega \ni q_s$; let $\|\vec{v}\| = \|\vec{u}_t(q_s)\| = v$ be the tangent velocity scalar field on $S \cap \Omega$. Let $\vec{v}^\perp = \vec{u}_t^\perp(q_s)$ be the tangent vector field on $S \cap \Omega \ni q_s$ such that $\{\vec{v}/v, \vec{v}^\perp/v, \vec{N}\}$ is an orthonormal, direct

basis (positively oriented), where the tangent velocity scalar $v = \|\vec{v}\| \neq 0$. Then, we also have with $q = p + \lambda \vec{N}(q_s) \in \Omega$ and $q_s \in S \cap \Omega$ that

$$\vec{u}_t(q) = \vec{u}_\parallel(q) \frac{\vec{v}}{v}(q_s) + \vec{u}_\perp(q) \frac{\vec{v}^\perp}{v}(q_s). \quad (1.3)$$

Let $u_3(q_s) = n$ be the vertical velocity scalar field on $S \cap \Omega \ni q_s$.

Similarly to Eq. (1.2), in $\Omega \ni q$ we have that

$$\begin{aligned} \vec{\omega}(q) &= \vec{\omega}_t(q) + \omega_3 \vec{N}(q) \\ &= \omega_1(q) \frac{\partial \vec{x}}{\partial \theta_1}(q_s) + \omega_2(q) \frac{\partial \vec{x}}{\partial \theta_2}(q_s) + \omega_3(q) \vec{N}(q_s), \end{aligned} \quad (1.4)$$

where $q_s \in S \cap \Omega$, $q = p + \lambda \vec{N}(q_s)$, $\lambda \in (-\varepsilon, \varepsilon)$, $\vec{\omega}_t(q)$ is the tangent component vector field of the vorticity in Ω to the surface S , that is $\vec{\omega}_t(q) \cdot \vec{N}(q_s) = 0$, and $\omega_3(q)$ is the scalar vertical component of the vorticity in Ω to S . If \vec{v}^\perp exists then we also have

$$\vec{\omega}_t(q) = \omega_\parallel(q) \frac{\vec{v}}{v}(q_s) + \omega_\perp(q) \frac{\vec{v}^\perp}{v}(q_s). \quad (1.5)$$

We will denote the vectorial derivative of any C^∞ -smooth function f on Ω with any vector $\vec{w} = w_\parallel(\vec{v}/v) + w_\perp(\vec{v}^\perp/v) + w_3 \vec{N} \in T_p(\mathbb{R}^3)$ at $p \in S$ with

$$\begin{aligned} D_{\vec{w}} f &= w_\parallel D_{\vec{v}/v} f + w_\perp D_{\vec{v}^\perp/v} f + w_3 D_{\vec{N}} f \\ &= w_\parallel f_{,\parallel} + w_\perp f_{,\perp} + w_3 f_{,3}, \end{aligned} \quad (1.6)$$

or the vectorial derivative of any C^∞ -smooth function f on $S \cap \Omega$ by any tangent vector $\vec{w} = w_\parallel(\vec{v}/v) + w_\perp(\vec{v}^\perp/v) \in T_p(S)$ at $p \in S$ with

$$D_{\vec{w}} f = w_\parallel D_{\vec{v}/v} f + w_\perp D_{\vec{v}^\perp/v} f = w_\parallel f_{,\parallel} + w_\perp f_{,\perp}. \quad (1.7)$$

Longuet-Higgins¹ shows, if S is a steady and free surface (i.e., $n=0$ and S is a free surface), the relationship between the tangent components, ω_\parallel , ω_\perp , of the vorticity on S and the geodesic torsion, τ_g , and the normal curvature, k_n , of the streamlines on S . Then, Herrera² generalizes the formulae of

^{a)}Electronic mail: blas.herrera@urv.net.